Total No. of Questions-8]

[Total No. of Printed Pages-6

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[5252]-517

S.E. (Mechanical/Auto.) (Second Semester) EXAMINATION, 2017 THEORY OF MACHINES 1

## (2015 COURSE)

Time : Three Hours

Maximum Marks: 70

- N.B. :- (i) Neat diagrams must be drawn wherever necessary.
  - (ii) Figures to the right indicate full marks.
  - (iii) Use of electronic pocket calculator is allowed.
  - (iv) Assume suitable data, if necessary.
- 1. (a) Define 'inversion' and explain with neat sketches any two inversions of single slider kinematic chain, giving their practical applications. [5]
  - (b) Describe with that sketches 'Dynamically Equivalent System. [5]

Or

- (a) Define Grashoff's law. State how it is helpful in classifying the four link mechanism into different types.
  - (b) The obliquity ratio of a vertical reciprocating engine is 4.5. The engine bore and stroke is 75 mm and 90 mm respectively. The engine rotates at 2200 rpm. The ross of the reciprocating parts is 1.2 kg. The gas pressure intensity is 5.5 bar. When it has moved 50° from the IDC or its power stroke, determine the piston effort. At what engine speed will be load on the gudgeon pin at crank pin be zero. ? [6]

P.T.O.

- (a) Describe with neat sketch the construction and working of Belt Transmission Dynamometer. [5]
  - (b) Two shafts P and Q are connected by Hookes coupling and have their axes included at 15°. If the shaft P rotates at a uniform speed of 1200 rpm, find the maximum acceleration of shaft Q and the angular positions of the shaft P at these instants.

Or

- 4. (a) Explain loop closure equation for four bar mechanism. [4
  - A single plate clutch, effective on both sides, is required to transmit 25 kW at 3000 rpm. Determine the outer and inner radii of friction surface if the coefficient of friction is 0.255, the ratio of radii is 1.25 and the maximum pressure is not to exceed 0.1 N/mm². Also determine the axial thrust to be provided by springs. Assume the theory of uniform wear [6]
- (a) Explain with the help of neat sketch the concept of Velocity Image Principle.
  - (b) The cofiguration of wrapping machine is shown in Fig. 1 Determine by using ICR method, the velocity of point P on bell crank lever PQR, if the crank rotates at 80 rad/s. The dimensions of various links are OA = 150 mm, AB = 950 mm,

[5252]-517

(b)

CB = 250 mm, BD = 400 mm, CR = 350 mm, QR = 250 mm and PQ = 600 mm. [11]

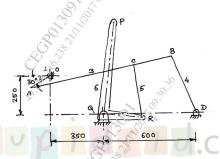


Fig. 1

Or

6. (a) State and explain Kennedy's theorem.

- [4]
- (b) The Fig. 2 shows four link mechanism. The link AB has angular velocity of 10.5 rad/s in counterclockwise direction. Find velocity of midpoint of link DGC and angular acceleration of link BCF.
  The dimensions of links are AD = 400 mm, AB = 50 mm,

[5252]-517 3 P.T.O.

BC = 66 mm, CD = 56 mm, BF = 45 mm, CF = 30 mm, CG = 24 mm and GD = 44 mm. [11]

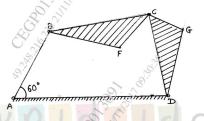
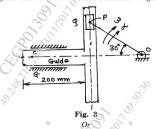


Fig. 2

- (a) Explain with neat drawing the procedure of Kleins construction to determine acceleration of piston of slider crank mechanism, when crank rotates with angular velocity ω and angular acceleration α.
  - (b) The Fig. 3 shows Scoth Yoke Mechanism. The length of the crank OP is 200 mm. At the instant shown in fig. the crank OP has angular velocity of 10 (ad/s and angular acceleration)

[5252]-517

of 30 rad/s2. Determine the acceleration of slider P in the guide and the horizontal acceleration of guide. [10]



- In the Fig. 4, show the Coriolis component of acceleration of link with direction for the following two cases:
  - Crank OA rotates in clockwise direction. Slider A moving towards fixed point Q. (ii)
    - Fig. P.T.O.

[4]

[5252]-517

- (b) In the IC engine mechanism the crank radius is 300 mm and length of connecting rod is 1050 mm. The crank is rotating with uniform angular velocity of 60 rad/s clockwise. Determine when crank at 120 from IDC by using Kliens construction.
  - (i) Acceleration of piston;
  - (ii) Angular acceleration of connecting rod.

The line of stroke of slider passes through fixed point. [11]

[5252]-517

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