

Robotics and AI

**QP Code : 8531**

(3 Hours)

[ Total Marks : 100 ]

- N.B.: (1) Question No. 1 is compulsory  
(2) Write any four questions out of remaining.  
(3) Assume suitable data if required.

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|-------|--|----|
| 1 (a) | Discuss Belief network.  | 5  |
| (b)   | Explain Heuristic function with example.                                     | 5  |
| (c)   | Describe robot workspace.  | 5  |
| (d)   | Explain Screw Transformation.  | 5  |
| 2 (a) | Explain A* search with example.  | 10 |
| (b)   | What is Uncertainty? Explain Bayesian network with example.                  | 10 |
| 3 (a) | Explain various methods of knowledge representation with example.            | 10 |
| (b)   | Explain steps in problem formulation with example.                           | 10 |
| 4 (a) | Obtain Inverse Kinematic solution for 4-axis SCARA Robot.                    | 10 |
| (b)   | Discuss various position sensors used in robots.                             | 10 |
| 5 (a) | Discuss partial order planning giving suitable example.                      | 10 |
| (b)   | Explain supervised, unsupervised and reinforcement learning with example.    | 10 |
| 6 (a) | Explain the structure of learning agent. What is role of critic in learning? | 10 |
| (b)   | Describe different types of environments applicable to AI agents.            | 10 |
| 7     | Write short note on  | 20 |
| (a)   | Properties of environment  |    |
| (b)   | Limitations of Hill-Climbing, A* algorithm                                   |    |
| (c)   | PROLOG   |    |
| (d)   | Crypt Arithmetic   |    |

**R.J-Con. 10699-15.**